Week 6 - Robot Sensors (6/3)

In week 5, we will go through the sensors used in robotics, in general, and those mounted on the TurtleBot3, in specific.

Thereafter, you will work on two exercises:

1. receive the IMU data from the TurtleBot
2. receive live video stream from the TurtleBot

To read: CORKE Chapter 3.4

Help: <https://au.mathworks.com/help/ros/ug/work-with-specialized-ros-messages.html>